

Factsheet: Vectors

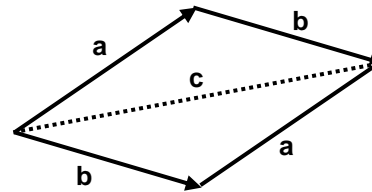
Definitions

In this factsheet vectors are depicted in bold type (e.g. \mathbf{a}) and scalars in italics (e.g. m).

A vector it has both magnitude *and* direction whereas a scalar only has magnitude

Parallelogram law of vector addition

If $\mathbf{a} + \mathbf{b} = \mathbf{c}$ then $\mathbf{a} = \mathbf{c} - \mathbf{b}$ and $\mathbf{b} = \mathbf{c} - \mathbf{a}$.



Vector properties and special vectors

Magnitude of a vector \mathbf{a} , written as $|\mathbf{a}|$ or a , represents the vector length and is a scalar.

Unit vectors have a magnitude of 1. A unit vector having the same direction as \mathbf{a} is written $\hat{\mathbf{a}}$ with the hat above the \mathbf{a} indicating the unit vector.

Specifically $\hat{\mathbf{a}} = \frac{\mathbf{a}}{a}$.

Rectangular unit vectors represent unit steps in the positive x , y and z -directions respectively.

Unit step in the x -direction is represented as $\hat{\mathbf{i}}$

Unit step in the y -direction is represented as $\hat{\mathbf{j}}$

Unit step in the z -direction is represented as $\hat{\mathbf{k}}$

Any vector can be described in terms of $\hat{\mathbf{i}}$, $\hat{\mathbf{j}}$ and $\hat{\mathbf{k}}$.

For example the vector \mathbf{a} can be written as $\mathbf{a} = a_1\hat{\mathbf{i}} + a_2\hat{\mathbf{j}} + a_3\hat{\mathbf{k}}$ where a_1 , a_2 and a_3 are the **components** of \mathbf{a} .

The magnitude of \mathbf{a} is from Pythagoras' theorem: $a = |\mathbf{a}| = \sqrt{a_1^2 + a_2^2 + a_3^2}$.

For three vectors \mathbf{a} , \mathbf{b} and \mathbf{c} and scalars m and n :

$$\mathbf{a} + \mathbf{b} = (a_1 + b_1)\hat{\mathbf{i}} + (a_2 + b_2)\hat{\mathbf{j}} + (a_3 + b_3)\hat{\mathbf{k}}$$

$$m\mathbf{a} = ma_1\hat{\mathbf{i}} + ma_2\hat{\mathbf{j}} + ma_3\hat{\mathbf{k}}$$

A **Position Vector** \mathbf{r} describes a journey from the origin to a particular coordinate. The coordinate (x, y, z) has a corresponding position vector $\mathbf{r} = x\hat{\mathbf{i}} + y\hat{\mathbf{j}} + z\hat{\mathbf{k}}$.

Dot or scalar product

The dot or scalar product of vectors $\mathbf{a} = a_1\hat{\mathbf{i}} + a_2\hat{\mathbf{j}} + a_3\hat{\mathbf{k}}$ and $\mathbf{b} = b_1\hat{\mathbf{i}} + b_2\hat{\mathbf{j}} + b_3\hat{\mathbf{k}}$ is defined as:

$$\mathbf{a} \cdot \mathbf{b} = ab \cos \theta = a_1b_1 + a_2b_2 + a_3b_3$$
$$\mathbf{a} \cdot \mathbf{a} = a^2 = a_1^2 + a_2^2 + a_3^2$$

where θ is the angle between \mathbf{a} and \mathbf{b} if they share the same start point. The result of a dot product is a scalar.

Specifically

$$\mathbf{a} \cdot \mathbf{b} = \mathbf{b} \cdot \mathbf{a}$$
$$\mathbf{a} \cdot (\mathbf{b} + \mathbf{c}) = \mathbf{a} \cdot \mathbf{b} + \mathbf{a} \cdot \mathbf{c}$$
$$\hat{\mathbf{i}} \cdot \hat{\mathbf{i}} = \hat{\mathbf{j}} \cdot \hat{\mathbf{j}} = \hat{\mathbf{k}} \cdot \hat{\mathbf{k}} = 1$$
$$\hat{\mathbf{i}} \cdot \hat{\mathbf{j}} = \hat{\mathbf{j}} \cdot \hat{\mathbf{k}} = \hat{\mathbf{i}} \cdot \hat{\mathbf{k}} = 0$$

If $\mathbf{a} \cdot \mathbf{b} = 0$ then \mathbf{a} and \mathbf{b} are perpendicular to each other.

Cross or vector product

The cross or vector product of vectors $\mathbf{a} = a_1\hat{\mathbf{i}} + a_2\hat{\mathbf{j}} + a_3\hat{\mathbf{k}}$ and $\mathbf{b} = b_1\hat{\mathbf{i}} + b_2\hat{\mathbf{j}} + b_3\hat{\mathbf{k}}$ is defined as:

$$\mathbf{a} \times \mathbf{b} = ab \sin \theta \hat{\mathbf{n}} = (a_2b_3 - a_3b_2)\hat{\mathbf{i}} - (a_1b_3 - a_3b_1)\hat{\mathbf{j}} + (a_1b_2 - a_2b_1)\hat{\mathbf{k}}$$

Specifically

$$\mathbf{a} \times \mathbf{b} = -\mathbf{b} \times \mathbf{a}$$
$$\mathbf{a} \times \mathbf{a} = \mathbf{0}$$
$$\mathbf{a} \times (\mathbf{b} + \mathbf{c}) = \mathbf{a} \times \mathbf{b} + \mathbf{a} \times \mathbf{c}$$
$$m(\mathbf{a} \times \mathbf{b}) = (m\mathbf{a}) \times \mathbf{b} = \mathbf{a} \times (m\mathbf{b}) = (\mathbf{a} \times \mathbf{b})m$$
$$\hat{\mathbf{i}} \times \hat{\mathbf{i}} = \hat{\mathbf{j}} \times \hat{\mathbf{j}} = \hat{\mathbf{k}} \times \hat{\mathbf{k}} = \mathbf{0}$$
$$\hat{\mathbf{i}} \times \hat{\mathbf{j}} = \hat{\mathbf{k}} \quad \hat{\mathbf{j}} \times \hat{\mathbf{k}} = \hat{\mathbf{i}} \quad \hat{\mathbf{k}} \times \hat{\mathbf{i}} = \hat{\mathbf{j}}$$

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